Artificial Intelligence Industrial Internet of Things based Robotic Warehouse Management System 人工智能工業物聯網機械人倉庫管理系統

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Special features 技術特點

- ▶ Can achieve better cycle time of order fulfillment 優化訂單狀態的反饋週期
- ▶ Fully visible over real-time demand and demand driven re-slotting technology 按實時需求自動部署機械人

Streamlining the efficiency, transparency and cost consideration on inbound logistics are critical factors for seamless delivery experience. It is always a challenge for supply chain to match real-time order with its order fulfillment. The cyber-physical solution that is fully visible over the inbound logistics by analyzing the real-time demand and improving racks allocation via collaborative swarm robots is developed.

The synergy between cyber-physical decisions and demand-responsive design can deal with the lack of agility in inbound logistics. Without sacrificing the capacity of order fulfillment performance, the demand-driven re-slotting and order fulfillment is performed simultaneously by the swarm mobile robots. Regarding the discrepancy between order fulfillment demand and predicting of rack re-slotting requirements, mobile robots with swarm intelligence is assigned with different role of tasks. With aids of the cyber-physical warehouse systems, order fulfillment status in actual operations and demand for e-Commerce products are synchronized and connected with "Digital Twin" to cope with the e-Commerce-level. dynamics.

The potential applications of predictive rearrangement racks in robo ic warehouse are using as express smart E-commerce electronic computerized parcel locker and withsmart locker function.

Swarm Robot Strategy 隨著電子商務消費模式興起,物流業在優化網購體驗和快速運送服務扮演 Conflict Resolution with Collision Free 著十分重要的角色。現時物流過程最大的挑戰是實時下單物流信 Cloud-based Trajectory Planning Swarm Robots Control System 息和貨物分配系統信息不完整以至耽誤整個流程。 理大團 隊研發了可持續把訂單狀態反饋到「數字雙胞胎」的虛擬 空間,然後透過群體智能算法推動機械人以實時重新部署 Divison-of-Robots 貨架擺放。此技術提升了機械人貨倉、物流需求和最後一 Batch and Cluster Order Picking Strate 哩運送服務的效益。另外也適用於自助快遞存取與智能儲物櫃等無 amous Mobile Robot 📃 Mobile Storage Back Autonomous Mobile Robot
 with Mobile Storage Back
 Autonomous Mobile Robot
 at Charging Station 人自助應用。 Putaway and Picking Workstation The Hong Kong Innovation and Technology **Development Office** POLYTECHNIC UNIVERSITY 創新及科技發展處 香港理工大學 PolyU ITDO Contact Us PolyU ITDO Ir Steven Lam, Manager

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