

## Subject Description Form

<b>Subject Code</b>	ME23001
<b>Subject Title</b>	Engineering Mechanics
<b>Credit Value</b>	3
<b>Level</b>	2
<b>Pre-requisite/ Co-requisite/ Exclusion</b>	Pre-requisite: AP10005 Physics I
<b>Objectives</b>	To provide students the fundamental mechanics concepts of equilibrium and motion for rigid structural systems.
<b>Intended Learning Outcomes</b>	<p>Upon completion of the subject, students will be able to:</p> <ol style="list-style-type: none"> <li>a. Apply the fundamental knowledge of mechanics to solve for forces and moments in simple systems.</li> <li>b. Distinguish the basic differences between diverse engineering systems and select the suitable design in achieving the engineering purposes.</li> <li>c. Employ engineering mechanics to solve the problems encountered in assignments and projects.</li> <li>d. Collaborate with peers in experiments and projects and present effectively the results of experiment or project.</li> </ol>
<b>Subject Synopsis/ Indicative Syllabus</b>	<p><b><i>Fundamentals of Mechanics</i></b> - Basic concepts of mechanics; Scalar and vectors; Vector algebra and vector components; Position, unit of force vectors; Two and three-dimensional force systems; Moment of a force about a point; Moment of a force about a line.</p> <p><b><i>Statics</i></b> - Equilibrium of a particle and the associated free-body diagrams; Equilibrium of a rigid body and the associated free-body diagram; Two and three force members equilibrium in three dimensions; Simple trusses: the method of joints; the method of sections; zero-force members; Internal forces developed in structural members; Shear and moment equations and diagrams in structural members; Relations between distributed load, shear and moment; Theory of dry friction; Systems with friction; Wedges; Belt friction; Rolling resistance.</p> <p><b><i>Equivalent Systems</i></b> - Determination of the resultant concurrent forces; Equivalent force/couple systems; Centre of gravity and centroid: by composite parts, by integration; Resultant of a general distributed force system; Moment of inertia of areas; Parallel-axis theorem for an area; Radius of gyration of an area; Calculation of moments of areas: by composite areas, by integration; Product of inertia for an area; Principles of virtual work.</p> <p><b><i>Dynamics</i></b> - Kinematics and kinetics of particles; rectilinear motion; plane curvilinear motion; relative motion; equation of motion.</p>

<b>Teaching/Learning Methodology</b>	<p>Lectures are used to deliver the fundamental knowledge in relation to the topics as described in the section subject synopsis (Outcomes a, b and c).</p> <p>Tutorials are used to illustrate the application of fundamental knowledge to practical situations (Outcomes a, b and c).</p> <p>Experiments are used to relate the concepts to practical applications and students are exposed to hand-on experience, proper use of equipment and application of analytical skills on interpreting experimental results (Outcomes c and d).</p> <table border="1" data-bbox="499 510 1249 779"> <thead> <tr> <th rowspan="2">Teaching/Learning Methodology</th> <th colspan="4">Outcomes</th> </tr> <tr> <th>a</th> <th>b</th> <th>c</th> <th>d</th> </tr> </thead> <tbody> <tr> <td>Lecture</td> <td>√</td> <td>√</td> <td>√</td> <td></td> </tr> <tr> <td>Tutorial</td> <td>√</td> <td>√</td> <td>√</td> <td></td> </tr> <tr> <td>Experiment/Projects</td> <td></td> <td></td> <td>√</td> <td>√</td> </tr> </tbody> </table>						Teaching/Learning Methodology	Outcomes				a	b	c	d	Lecture	√	√	√		Tutorial	√	√	√		Experiment/Projects			√	√																		
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<b>Reading List and References</b>	<ol style="list-style-type: none"><li>1. R.C. Hibbeler, Engineering Mechanics – Statics, Prentice Hall, latest edition.</li><li>2. A. Pytel, J. Kiusalaas, Engineering Mechanics – Statics, Stamford, CT: Cengage Learning, latest edition.</li></ol>
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*Revised June 2020*