

Error bound for conic feasibility problems: case studies on the exponential cone

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(Joint work with Scott B. Lindstrom and Bruno F. Lourenço)

Conic programming problem

Conic program: Let \mathcal{K} be a closed convex cone in a Euclidean space \mathcal{E} , $c \in \mathcal{E}$, \mathcal{A} be a linear map on \mathcal{E} and $b \in \text{Range}(\mathcal{A})$.

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$$K_{\text{exp}} := \{x \in \mathbb{R}^3 \mid x_2 > 0, x_3 \geq x_2 e^{x_1/x_2}\} \cup \{(x_1, 0, x_3) \mid x_1 \leq 0, x_3 \geq 0\}.$$

- ★ Epigraph of (the closure of) the perspective function of $z \mapsto \exp(z)$.
- ★ Recent addition to **MOSEK** and other conic solvers.
- ★ Has applications in relative entropy optimization (**Chandrasekaran, Shah '17**).

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- Product cones of the above...

Why “exotic” cones?

- Richer **modeling power**. For example,

$$t \geq \ln \left(\sum_{i=1}^n e^{x_i} \right) \iff \sum_{i=1}^n z_i \leq 1 \text{ and } (z_i, 1, x_i - t) \in K_{\text{exp}} \forall i.$$

See <https://docs.mosek.com/cheatsheets/conic.pdf>.

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- These and many other exotic cones have nice **logarithmically homogeneous self-concordant barrier functions** for the adaptation of existing IPM routines. (Coey, Kapelevich, Vielma '21)

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Find $x \in \mathcal{K} \cap (\mathcal{L} + a)$.

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For instance, consider

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Assume the solution set S is **nonempty** and denote the optimal value by v .

Then

$$S = \mathcal{K} \cap (\mathcal{L} + a),$$

where

$$\mathcal{L} + a = \{x : Ax = b, \langle c, x \rangle = v\}.$$

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- $d(x, \mathcal{K} \cap (\mathcal{L} + a))$ is a measure on how “feasible” x is. Hard to compute!
- Typically, $d(x, \mathcal{K})$ and $d(x, \mathcal{L} + a)$ are relatively easier to compute.
- Is x “a good soln.” when $\max\{d(x, \mathcal{K}), d(x, \mathcal{L} + a)\}$ is small?

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Error bounds

Definition: Let $\theta \in (0, 1]$. We say that $\{\mathcal{K}, \mathcal{L} + a\}$ satisfies a **(uniform) Hölderian error bound** with exponent θ if for every bounded set B , there exists $c_B > 0$ such that

$$d(x, \mathcal{K} \cap (\mathcal{L} + a)) \leq c_B (\max\{d(x, \mathcal{K}), d(x, \mathcal{L} + a)\})^\theta \quad \forall x \in B.$$

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Examples:

- If \mathcal{K} is polyhedral, Lipschitz error bound holds. (Hoffman '57)
- If $(\mathcal{L} + \mathbf{a}) \cap \text{ri } \mathcal{K} \neq \emptyset$, Lipschitz error bound holds. (Bauschke, Borwein '96)

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- If $\mathcal{K} = \mathcal{S}_+^n$, **Hölderian error bound** with exponent $2^{-(\ell-1)}$ holds (Sturm '00); here ℓ has to do with **facial reduction**. (Borwein, Wolkowicz '81)

Faces and facial reduction

Definition: A sub-cone $\mathcal{F} \subseteq \mathcal{K}$ is called

- a face if $x, y \in \mathcal{K}$ and $x + y \in \mathcal{F}$ implies $x, y \in \mathcal{F}$;
- an **exposed** face if $\exists z \in \mathcal{K}^*$ such that $\mathcal{F} = \mathcal{K} \cap \{z\}^\perp$.

Note: Recall that $\mathcal{K}^* := \{x \mid \langle x, y \rangle \geq 0 \ \forall y \in \mathcal{K}\}$.

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Theorem 1. (Borwein, Wolkowicz '81, Lourenço, Muramatsu, Tsuchiya '18)

Suppose $\mathcal{K} \cap (\mathcal{L} + a) \neq \emptyset$. Then there exists a chain of faces

$$\mathcal{F}_\ell \subsetneq \cdots \subsetneq \mathcal{F}_1 = \mathcal{K}$$

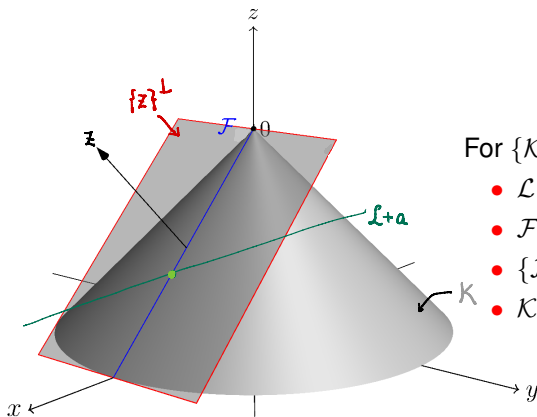
and vectors $\{z_1, \dots, z_{\ell-1}\}$ satisfying

- For all $i \in \{1, \dots, \ell - 1\}$,

$$z_i \in \mathcal{F}_i^* \cap \mathcal{L}^\perp \cap \{a\}^\perp \quad \text{and} \quad \mathcal{F}_{i+1} = \mathcal{F}_i \cap \{z_i\}^\perp.$$

- $\mathcal{F}_\ell \cap (\mathcal{L} + a) = \mathcal{K} \cap (\mathcal{L} + a)$ and $\{\mathcal{F}_\ell, \mathcal{L} + a\}$ satisfies a **Lipschitz error bound**.

Facial reduction: Illustration



The picture is provided by B. F. Lourenço.

For $\{K, \mathcal{L} + a\}$:

- $\mathcal{L} + a \subseteq \{z\}^\perp$;
- $\mathcal{F} = K \cap \{z\}^\perp$;
- $\{\mathcal{F}, \mathcal{L} + a\}$ has Lip. err. bd.
- $K \cap (\mathcal{L} + a) = \mathcal{F} \cap (\mathcal{L} + a)$.

Sturm's error bounds and facial reduction

Key observation: (Sturm '00, Lourenço '21)

Let $\mathcal{F} \trianglelefteq \mathcal{S}_+^n$ and $z \in \mathcal{F}^*$. Then $\exists \kappa > 0$ such that for all x ,

$$d(x, \mathcal{F} \cap \{z\}^\perp) \leq \kappa \epsilon + \kappa \sqrt{\epsilon \|x\|},$$

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Error bound for $\{\mathcal{S}_+^n, (\mathcal{L} + a)\}$ follows from induction: For $x \in B$,

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Facial residual function

Definition: (Lourenço '21, Lindstrom, Lourenço, P. '22)

Let $\mathcal{F} \trianglelefteq \mathcal{K}$ and $z \in \mathcal{F}^*$. Suppose $\psi : \mathbb{R}_+ \times \mathbb{R}_+ \rightarrow \mathbb{R}_+$ satisfies

- ψ is nondecreasing in each argument and $\psi(0, t) = 0 \forall t \in \mathbb{R}_+$;
- It holds that

$$d(x, \mathcal{F} \cap \{z\}^\perp) \leq \psi(\max\{d(x, \mathcal{F}), d(x, \{z\}^\perp)\}, \|x\|) \quad \forall x \in \text{span } \mathcal{F}.$$

Then ψ is called a **1-step facial residual function** for \mathcal{F} and z .

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Remarks:

- For $\mathcal{K} = \mathcal{S}_+^n$, we have $\psi(s, t) = \kappa \cdot (s + \sqrt{st})$ for some $\kappa > 0$.
- Induction arguments show that error bound can be derived given the face chain from **facial reduction** and by composing **1-step facial residual functions**. (Lindstrom, Lourenço, P. '22)

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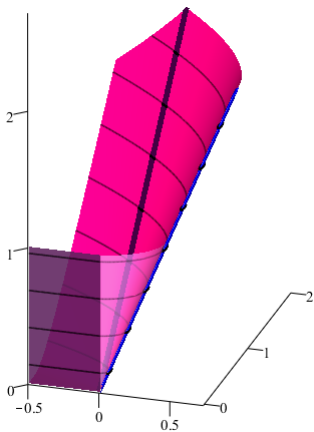
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- Two key ingredients: For each **nonpolyhedral** \mathcal{F} ,
 - ★ Identify all its **exposed faces**.
 - ★ Obtain all **1-step facial residual functions**: Depends on \mathcal{F} and z .

Exponential cone

$$K_{\text{exp}} = \{x \in \mathbb{R}^3 \mid x_2 > 0, x_3 \geq x_2 e^{x_1/x_2}\} \cup \{(x_1, 0, x_3) \mid x_1 \leq 0, x_3 \geq 0\}.$$



Faces of exponential cone

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Nontrivial exposed faces: (Lindstrom, Lourenço, P. '22)

- (Infinitely many) 1-D face exposed by a **unique** (up to scaling) $z \in \partial K_{\text{exp}}^* \setminus \{0\}$:

$$\mathcal{F}_\beta := \{(t(1 - \beta), t, te^{1-\beta}) \mid t \geq 0\} \text{ for each } \beta \in \mathbb{R}.$$

- An **exceptional** extreme ray exposed by any $z \in \{(0, z_2, z_3) \mid z_2 \geq 0, z_3 > 0\} \subset \partial K_{\text{exp}}^* \setminus \{0\}$:

$$\mathcal{F}_\infty := \{(x_1, 0, 0) \mid x_1 \leq 0\}.$$

- A unique 2-D face exposed **uniquely** (up to scaling) by $(0, 1, 0)$:

$$\mathcal{F}_{-\infty} := \{(x_1, 0, x_3) \mid x_1 \leq 0, x_3 \geq 0\}.$$

1-FRFs for exponential cone

1-FRFs: (Lindstrom, Lourenço, P. '22) Assume $\|z\| = 1$.

- (Infinitely many) 1-D face exposed by a **unique** $z \in \partial K_{\text{exp}}^* \setminus \{0\}$:

$$\psi(s, t) = s + \kappa(t) \cdot \sqrt{2s},$$

where $\kappa(\cdot)$ is **nonnegative nondecreasing**.

- The **exceptional** extreme ray \mathcal{F}_{∞} :

$$\psi(s, t) = \begin{cases} s + 2\kappa(t)s & \text{if } z_2 > 0, \\ s + \kappa(t) \cdot g_{\infty}(2s) & \text{if } z_2 = 0, \end{cases}$$

where $\kappa(\cdot)$ is **nonnegative nondecreasing**, and $g_{\infty} : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ is

$$g_{\infty}(s) := \begin{cases} 0 & \text{if } s = 0, \\ -(\ln s)^{-1} & \text{if } 0 < s \leq e^{-2}, \\ 0.25(1 + e^2 s) & \text{else.} \end{cases}$$

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$$\psi(s, t) = s + \kappa(t) \cdot g_{-\infty}(2s),$$

where $\kappa(\cdot)$ is **nonnegative nondecreasing**, $g_{-\infty} : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ is

$$g_{-\infty}(s) := \begin{cases} 0 & \text{if } s = 0, \\ -s \ln s & \text{if } 0 < s \leq e^{-2}, \\ s + e^{-2} & \text{else.} \end{cases}$$

Remark:

- As all nontrivial exposed faces are polyhedral, $\ell \leq 2$. The final error bound has the same “**order of magnitude**” as the 1-FRFs.
- As $s \downarrow 0$: $-(\ln s)^{-1} \rightarrow 0$ **slower** than s^α for any $\alpha \in (0, 1]$;
 $-s \ln s \rightarrow 0$ **faster** than s^α for any $\alpha \in (0, 1)$, but is **slower** than s .
- These 1-FRFs are asymptotically the “**best**”. (Lindstrom, Lourenço, P. '22)

Conclusion

Conclusion:

- Facial reduction and $\mathbb{1}$ -FRFs are two key ingredients for deriving error bounds.
- Error bounds for K_{exp} feasibility problem.

References:

- S. B. Lindstrom, B. F. Lourenço and T. K. Pong.
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Thanks for coming! ☺