

```
In [1]: # an ellipse given in parametric form
# that the ellipse is tilted and shifted
# with centre at (x=c1=2, y=c2=3)
# and major radius r1=4
# and minor radius r2=1
# and tilted by angle alpha=pi/3
c1=2
c2=3
r1=4
r2=1
alpha=pi/3
x(t)=r1*cos(alpha)*cos(t)-r2*sin(alpha)*sin(t)+c1
y(t)=r1*sin(alpha)*cos(t)+r2*cos(alpha)*sin(t)+c2
```

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In [2]: # define a fixed point P at (ptx=4, pty=3)
#
ptx=4
pty=3
```

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In [3]: # define the square distance DS(t) between the point
# and the ellipse with parameter t
#
DS(t)=(x(t)-ptx)^2+(y(t)-pty)^2
```

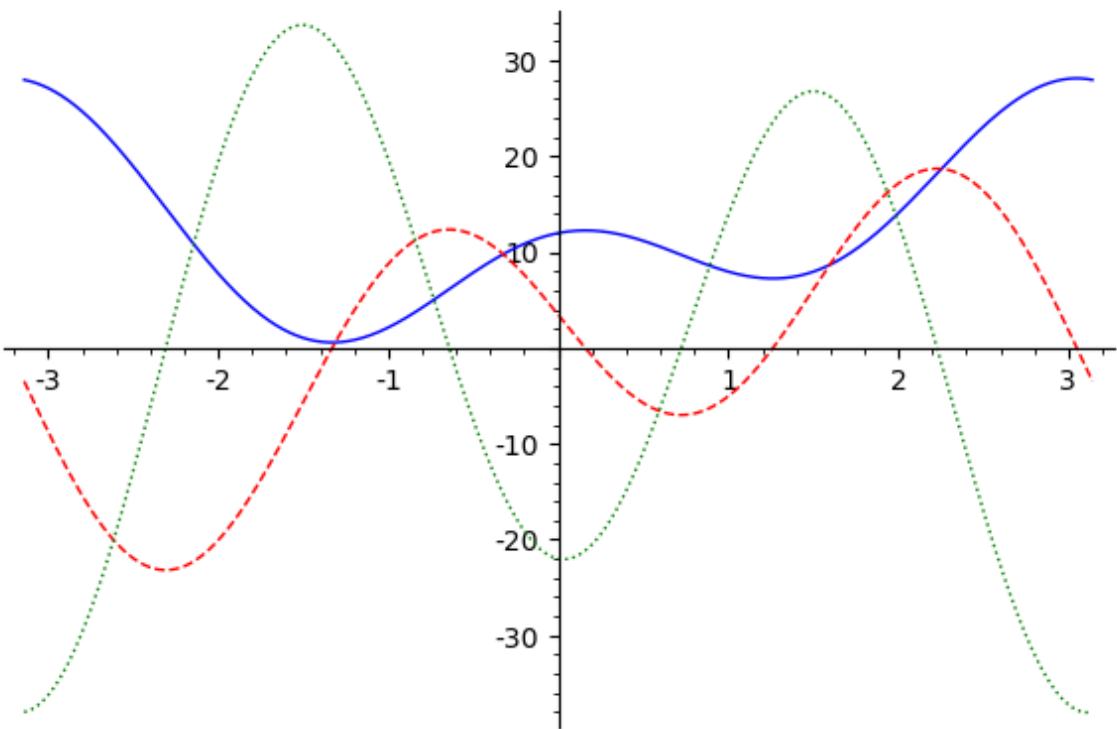
```
In [4]: # to find the closest point on the ellipse to point P,
# we find t minimizing DS
# thus, we differentiate DS w.r.t. t,
# let it equals zero, and solve for t
#
show(solve(diff(DS(t),t)==0,t))
```

Out[4]:

$$\left[ \sin(t) = \frac{\sqrt{3} \cos(t)}{15 \cos(t) - 4} \right]$$

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In [5]: p0=plot(DS(t),t,-pi,pi)
p1=plot(diff(DS(t),t),t,-pi,pi,rgbcolor='red',linestyle = "dashed")
p2=plot(diff(DS(t),t,2),t,-pi,pi, rgbcolor='green', linestyle = "dotted" )
p0+p1+p2
```

Out[5]:



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In [6]: # since CoCalc cannot show analytic exact answer for t
# we need to find t numerically
#
t0=(diff(DS(t),t)==0).find_root(-2,-1,t)
show(t0)
```

Out[6]: -1.3301502523524125

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In [7]: t1=(diff(DS(t),t)==0).find_root(0,1,t)
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In [8]: t2=(diff(DS(t),t)==0).find_root(1,2,t)
```

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In [9]: t3=(diff(DS(t),t)==0).find_root(3,4,t)
```

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In [10]: show(RR(x(t0)))
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Out[10]: 3.31773045452361

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In [11]: show(RR(y(t0)))
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Out[11]: 3.34000770082227

```
In [12]: show(RR(sqrt(DS(t0))))
```

Out[12]: 0.762297166007466

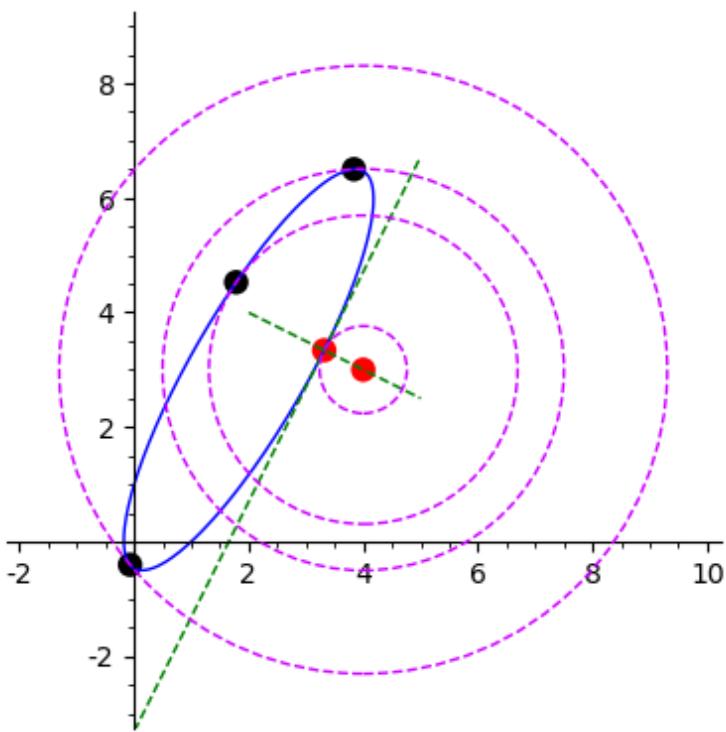
```
In [13]: # find the slope of tangent line m
#  $m(t) = dy/dx = (dy/dt)/(dx/dt)$ 
#
var('yy xx')
xdash(t)=diff(x(t),t)
ydash(t)=diff(y(t),t)
m(t)=ydash(t)/xdash(t)
```

```
In [14]: # tangent line at  $t=t_0$ 
#
tangent(xx)=solve((yy-y(t0))/(xx-x(t0))==m(t0),yy)[0].rhs()
```

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In [15]: # normal line at  $t=t_0$ 
#
normal(xx)=solve((yy-y(t0))/(xx-x(t0))==(-1/m(t0)),yy)[0].rhs()
```

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In [16]: p1=parametric_plot( (x(t), y(t)), (t, -pi, pi) )
p2=plot(tangent(xx),xx,0,5, rgbcolor='green', linestyle = "dashed")
p3=plot(normal(xx),xx,2,5, rgbcolor='green', linestyle = "dashed")
cplt0=circle((ptx,pty),sqrt(DS(t0)),color=hue(0.8), linestyle = "dashed")
cplt1=circle((ptx,pty),sqrt(DS(t1)),color=hue(0.8), linestyle = "dashed")
cplt2=circle((ptx,pty),sqrt(DS(t2)),color=hue(0.8), linestyle = "dashed")
cplt3=circle((ptx,pty),sqrt(DS(t3)),color=hue(0.8), linestyle = "dashed")
pt0 = point((x(t0),y(t0)), rgbcolor='red', pointsize=80)
pt00 = point((ptx,pty), rgbcolor='red', pointsize=80)
pt1 = point((x(t1),y(t1)), rgbcolor='black', pointsize=80)
pt2 = point((x(t2),y(t2)), rgbcolor='black', pointsize=80)
pt3 = point((x(t3),y(t3)), rgbcolor='black', pointsize=80)
plotall=p1+p2+p3+pt0+pt00+pt1+pt2+pt3+cplt0+cplt1+cplt2+cplt3
(plotall).show(xmin=-2, xmax=10, ymin=-3, ymax=9, aspect_ratio=1)
```

Out[16]:



In [0]: