Recent Developments in Nonlinear Optimization Theory

> Defeng Sun Department of Mathematics National University of Singapore Republic of Singapore

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(1)

2 Variational Analysis on Metric Projectors Over Closed Convex Sets

Let Z be a finite-dimensional Hilbert vector space equipped with a scalar product $\langle \cdot, \cdot \rangle$ and its induced norm $\|\cdot\|$ and D be a nonempty closed convex set in Z. For any $z \in Z$, let $\Pi_D(z)$ denote the metric projection of z onto D:

$$\min \quad \frac{1}{2} \langle y - z, y - z \rangle$$

s.t. $y \in D$.

The operator $\Pi_D : Z \to Z$ is called the metric projection operator or metric projector over D.

(2)

Proposition 2.1 Let D be a nonempty closed convex set in Z. Then the point $y \in D$ is an optimal solution to (1) if and only if it satisfies

$$\langle z-y, d-y \rangle \le 0 \quad \forall \ d \in D.$$

Proof. " \Rightarrow " Suppose that $y \in D$ is an optimal solution to (1). Let d be an arbitrary point in D. Then $y_t := (1 - t)y + td \in D$ for any $t \in [0, 1]$. This, together with the fact that y is an optimal solution, implies that

$$||z - y_t||^2 \ge ||z - y||^2 \quad \forall t \in [0, 1],$$

which further implies

$$||(1-t)(z-y) + t(z-d)||^2 \ge ||z-y||^2 \quad \forall t \in [0,1].$$

$$(t^{2} - 2t)\|z - y\|^{2} + 2t(1 - t)\langle z - y, z - d\rangle + t^{2}\|z - d\|^{2} \ge 0 \ \forall t \in [0, 1].$$

By taking $t \downarrow 0$ and dividing t on both sides of the above equation, we obtain

$$-2||z-y||^2 + 2\langle z-y, z-d \rangle \ge 0$$

which turns into (2).

" \Leftarrow " Suppose that $y \in D$ satisfies (2). Assume on the contrary that y does not solve (1). Then we have by the assumption,

$$\langle z - y, \Pi_D(z) - y \rangle \le 0$$

and by the sufficiency part,

$$\langle z - \Pi_D(z), y - \Pi_D(z) \rangle \leq 0.$$

Summing up the above two inequalities leads to

$$\langle \Pi_D(z) - y, \Pi_D(z) - y \rangle \le 0.$$

This implies that $y = \prod_D(z)$. The contradiction shows that y solves (1).

Note that Proposition 2.1 holds even if Z is infinite-dimensional. If D is a nonempty closed convex cone, then (2) is equivalent to

$$\langle z - \Pi_D(z), \Pi_D(z) \rangle = 0 \quad \& \quad \langle z - \Pi_D(z), d \rangle \le 0 \quad \forall \ d \in D.$$
 (3)

Proposition 2.2 Let D be a nonempty closed convex set in Z. Then the metric projector $\Pi_D(\cdot)$ satisfies

 $\langle y - z, \Pi_D(y) - \Pi_D(z) \rangle \ge \|\Pi_D(y) - \Pi_D(z)\|^2 \quad \forall \ y, z \in \mathbb{Z}.$ (4)

Note that (4) implies

$$\|\Pi_D(y) - \Pi_D(z)\| \le \|y - z\| \quad \forall \ y, z \in Z.$$

Proof. Let $y, z \in Z$. Then by Proposition 2.1, we have

$$\langle z - \Pi_D(z), \Pi_D(y) - \Pi_D(z) \rangle \le 0$$

and

$$\langle y - \Pi_D(y), \Pi_D(z) - \Pi_D(y) \rangle \leq 0$$

Summing them up gives the desired inequality (4).

The metric projector $\Pi_D(\cdot)$ is only globally Lipschitz continuous and is not differentiable everywhere, but we have

Proposition 2.3 Let D be a nonempty closed convex set in Z. Let

$$\theta(z) := \frac{1}{2} ||z - \Pi_D(z)||^2, \quad z \in \mathbb{Z}.$$

Then θ is continuously differentiable with

 $\nabla \theta(z) = z - \Pi_D(z), \quad z \in \mathbb{Z}.$



and similarly

$$\begin{aligned} \theta(z + \Delta z) - \theta(z) \\ &= \frac{1}{2} \langle \Delta z - [\Pi_D(z + \Delta z) - \Pi_D(z)], Q(z + \Delta z) + Q(z) \rangle \\ &= \langle \Delta z - [\Pi_D(z + \Delta z) - \Pi_D(z)], Q(z + \Delta z) \rangle + O(||\Delta z||^2) \\ &= \langle Q(z + \Delta z), \Delta z \rangle - \langle \Pi_D(z + \Delta z) - \Pi_D(z), Q(z + \Delta z) \rangle + O(||\Delta z||^2) \\ &= \langle Q(z), \Delta z \rangle + \langle \Pi_D(z) - \Pi_D(z + \Delta z), Q(z + \Delta z) \rangle + O(||\Delta z||^2) \\ &\leq \langle Q(z), \Delta z \rangle + O(||\Delta z||^2) \quad (by (2)) \,. \end{aligned}$$

Thus θ is Fréchet differentiable at z with

$$\nabla \theta(z) = z - \Pi_D(z) \,.$$

The continuity of $\nabla \theta(\cdot)$ follows from the global Lipschitz continuity of $\Pi_D(\cdot)$.

Recall that the normal cone $\mathcal{N}_D(y)$ at y in the sense of convex analysis is

$$\mathcal{N}_D(y) = \begin{cases} \{d \in Y : \langle d, z - y \rangle \le 0 \ \forall z \in D\} & \text{if } y \in D, \\ \emptyset & \text{if } y \notin D. \end{cases}$$

Proposition 2.4 Let D be a nonempty closed convex set in Z. Then a point $\mu \in \mathcal{N}_D(y)$ if and only if

$$y = \Pi_D(y + \mu) \,.$$

(5)

Note that $\mu \in \mathcal{N}_D(y)$ already implies that $y \in D$.

Proof. " \Rightarrow " Suppose that $\mu \in \mathcal{N}_D(y)$. Then $y \in D$ and $\langle \mu, z - y \rangle \leq 0 \quad \forall z \in D$.

Thus,

$$\langle (y+\mu)-y, z-y \rangle \leq 0 \quad \forall \, z \in D \,,$$

which, according to Proposition 2.1, implies $y = \prod_D (y + \mu)$.

"
—" Suppose that $y = \prod_D (y + \mu)$. Then $y \in D$. By Proposition 2.1, we have

$$\langle (y+\mu) - y, z-y \rangle \le 0 \quad \forall \, z \in D \,,$$

i.e.,

$$\langle \mu, z - y \rangle \leq 0 \quad \forall \, z \in D \,.$$

That is, $\mu \in \mathcal{N}_D(y)$.

(6)

Proposition 2.5 Let D be a nonempty closed convex cone in Z and $D^o := -D^*$ be the polar of D. Then any $z \in Z$ can be uniquely decomposed into

 $z = \Pi_D(z) + \Pi_{D^o}(z) \,.$

Proof. Let $u := z - \prod_D(z)$. By (3), we have

 $\langle u, \Pi_D(z) \rangle = 0 \quad \& \quad \langle u, d \rangle \le 0 \quad \forall d \in D.$

Thus $u \in D^o$, $\langle z - u, u \rangle = 0$, and

 $\langle z - u, w \rangle = \langle z - (z - \Pi_D(z)), w \rangle = \langle \Pi_D(z), w \rangle \le 0 \quad \forall w \in D^o.$

Hence, $u = \prod_{D^o}(z)$. The uniqueness of the decomposition is obvious.

For A and B in \mathcal{S}^p , define

$$\langle A, B \rangle := \operatorname{Tr} \left(A^T B \right) = \operatorname{Tr} \left(A B \right) ,$$

where "Tr" denotes the trace of a square matrix (i.e., the sum of all diagonal elements of the symmetric matrix). Let $A \in S^p$ have the following spectral decomposition

 $A = P\Lambda P^T,$

where Λ is the diagonal matrix of eigenvalues of A and P is a corresponding orthogonal matrix of orthonormal eigenvectors.

Let $A_+ := P\Lambda_+ P^T.$ Then, $\langle A - A_+, A_+ \rangle = \langle \Lambda - \Lambda_+, \Lambda_+ \rangle = 0$ and $\langle A - A_+, H \rangle = \langle \Lambda - \Lambda_+, P^T H P \rangle \le 0 \quad \forall H \in \mathcal{S}^p_+.$ Thus, by (3), we obtain that : $\Pi_{\mathcal{S}^p_+}(A) = A_+ = P\Lambda_+ P^T \,.$

Let $\Xi : \mathcal{O} \subseteq Y \to Z$ be a locally Lipschitz continuous function on the open set \mathcal{O} , where Y is another finite-dimensional **REAL** Hilbert space.

Then by the Rademacher theorem, Ξ is almost everywhere (in the Lebesgue sense) Fréchet differential in \mathcal{O} . We denote by \mathcal{O}_{Ξ} the set of points in \mathcal{O} where Ξ is Fréchet differentiable. If $\mathcal{O} \equiv Y$, we use \mathcal{D}_{Ξ} to represent Y_{Ξ} . Then Clarke's generalized Jacobian of Ξ at y is:

 $\partial \Xi(y) := \operatorname{conv} \{ \partial_B \Xi(y) \},$

where "conv" denotes the convex hull and

$$\partial_B \Xi(y) := \{ V : V = \lim_{k \to \infty} \mathcal{J}\Xi(y^k), \, y^k \to y, \, y^k \in \mathcal{O}_\Xi \}.$$

Proposition 2.6 Let D be a nonempty closed convex set in Z. For any $y \in Z$ and $V \in \partial \Pi_D(y)$,

(i) V is self-adjoint;

(ii)
$$\langle d, Vd \rangle \geq 0 \quad \forall d \in Z; and$$

(iii) $\langle Vd, d-Vd \rangle \geq 0 \quad \forall d \in \mathbb{Z}.$

Proof. (i) Define $\varphi : Z \to \Re$ by

$$\varphi(z) := \frac{1}{2} [\langle z, z \rangle - \langle z - \Pi_D(z), z - \Pi_K(z) \rangle], \quad z \in \mathbb{Z}.$$

Then, by Proposition 2.3, φ is continuously differentiable with

$$\nabla \varphi(z) = z - [z - \Pi_D(z)] = \Pi_D(y), \quad z \in \mathbb{Z}.$$

It then follows that if $\Pi_D(\cdot)$ is Fréchet differentiable at some z, then $\mathcal{J}\Pi_D(z)$ is self-adjoint. Thus, V, as the limit of $\mathcal{J}\Pi_D(y^k)$ for some $y^k \in \mathcal{D}_{\Pi_D}$ converging to y, is also self-adjoint.

(ii) is a special case of (iii).

(iii) First, we consider $z \in \mathcal{D}_{\Pi_D}$. By Proposition 2.2, for any $d \in Z$ and $t \geq 0$, we have

 $\langle \Pi_D(z+td) - \Pi_D(z), td \rangle \ge ||\Pi_D(z+td) - \Pi_D(z)||^2$, for all $t \ge 0$. Hence,

$$\langle \mathcal{J}\Pi_D(z)d,d\rangle \ge \langle \mathcal{J}\Pi_D(z)d,\mathcal{J}\Pi_D(z)d\rangle.$$
 (7)

Next, let $V \in \partial \Pi_D(y)$. Then, by Carathéodory's theorem, there exist a positive integer $\kappa > 0$, $V^i \in \partial_B \Pi_D(y)$, $i = 1, 2, ..., \kappa$ such that

$$V = \sum_{i=1}^{\kappa} \lambda_i V^i \,,$$

where $\lambda_i \ge 0$, $i = 1, 2, ..., \kappa$, and $\sum_{i=1}^{\kappa} \lambda_i = 1$.

Let
$$d \in Z$$
. For each $i = 1, ..., \kappa$ and $k = 1, 2, ...,$ there exists $y^{i_k} \in \mathcal{D}_{\Pi_D}$ such that

$$|y - y^{i_k}|| \le 1/k$$

and

$$|\mathcal{J}\Pi_D(y^{i_k}) - V^i|| \le 1/k$$

By (7), we have

 $\langle \mathcal{J}\Pi_D(y^{i_k})d,d\rangle \geq \langle \mathcal{J}\Pi_D(y^{i_k})d,\mathcal{J}\Pi_D(y^{i_k})d\rangle.$

Hence,

 $\langle V^i d, d \rangle \ge \langle V^i d, V^i d \rangle,$

and so,

$$\sum_{i=1}^{\kappa} \lambda_i \langle V^i d, d \rangle \ge \sum_{i=1}^{\kappa} \lambda_i \langle V^i d, V^i d \rangle.$$
(8)

Define
$$\theta(z) := ||z||^2$$
, $z \in Z$. By the convexity of θ , we have

$$\theta\Big(\sum_{i=1}^{\kappa}\lambda_i V^i d\Big) \le \sum_{i=1}^{\kappa}\lambda_i \theta(V^i d) = \sum_{i=1}^{\kappa}\lambda_i \langle V^i d, V^i d \rangle = \sum_{i=1}^{\kappa}\lambda_i ||V^i d||^2.$$

Hence,

$$\sum_{i=1}^{\kappa} \lambda_i ||V^i d||^2 \ge \left\langle \sum_{i=1}^{\kappa} \lambda_i V^i d, \sum_{i=1}^{\kappa} \lambda_i V^i d \right\rangle.$$
(9)

By using (8) and (9), we obtain for all $d \in Z$ that

 $\langle Vd, d \rangle \geq \langle Vd, Vd \rangle.$

The proof is completed.

Recall that if $A \in \mathcal{S}^p$ has the following spectral decomposition

$$A = P\Lambda P^T,$$

where Λ is the diagonal matrix of eigenvalues of A and P is a corresponding orthogonal matrix of orthonormal eigenvectors, then

$$A_+ = \Pi_{\mathcal{S}^p_+}(A) = P\Lambda_+ P^T.$$

Define

$$\alpha := \{i : \lambda_i > 0\}, \ \beta := \{i : \lambda_i = 0\}, \ \gamma := \{i : \lambda_i < 0\}.$$

Write

$$\Lambda = \begin{bmatrix} \Lambda_{\alpha} & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & \Lambda_{\gamma} \end{bmatrix} \text{ and } P = \begin{bmatrix} P_{\alpha} & P_{\beta} & P_{\gamma} \end{bmatrix}.$$

Define $U \in \mathcal{S}^p$:

$$U_{ij} := \frac{\max\{\lambda_i, 0\} + \max\{\lambda_j, 0\}}{|\lambda_i| + |\lambda_j|}, \quad i, j = 1, \dots, p,$$

where 0/0 is defined to be 1.

The operator $\Pi_{\mathcal{S}^p_+}(\cdot)$ is <u>strongly semismooth</u> at A, i.e., in addition to the directional differentiability of $\Pi_{\mathcal{S}^p_+}(\cdot)$ at A, for any $H \in \mathcal{S}^p$ and $V \in \partial \Pi_{\mathcal{S}^p_+}(A + H)$ we have

$$\Pi_{\mathcal{S}^{p}_{+}}(A+H) - \Pi_{\mathcal{S}^{p}_{+}}(A) - V(H) = O(||H||^{2}).$$
(10)

The directional derivative of $\Pi_{\mathcal{S}^p_+}(\cdot)$ at A has a very compact form

$$\Pi_{\mathcal{S}^{p}_{+}}^{\prime}(A;H) = P \begin{bmatrix} P_{\alpha}^{T}HP_{\alpha} & P_{\alpha}^{T}HP_{\beta} & U_{\alpha\gamma} \circ P_{\alpha}^{T}HP_{\gamma} \\ P_{\beta}^{T}HP_{\alpha} & \Pi_{\mathcal{S}^{|\beta|}_{+}}(P_{\beta}^{T}HP_{\beta}) & 0 \\ P_{\gamma}^{T}HP_{\alpha} \circ U_{\alpha\gamma}^{T} & 0 & 0 \end{bmatrix} P^{T}$$

where \circ denotes the Hadamard product. Note that $\Pi'_{\mathcal{S}^p_+}(A; H)$ does not depend on any particularly chosen P.

The following result needs a long but not very complicated proof.

Proposition 2.7 Let

 $\Theta(\cdot) := \Pi'_{\mathcal{S}^p_+}(A; \cdot).$

It holds that

 $\partial_B \Pi_{\mathcal{S}^p_+}(A) = \partial_B \Theta(0).$

Proposition 2.8 Let $\Psi : X \to Y$ be continuously differentiable on an open neighborhood \widehat{N} of \overline{x} and $\Xi : \mathcal{O} \subseteq Y \to Z$ be a locally Lipschitz continuous function on an open set \mathcal{O} containing $\overline{y} := \Psi(\overline{x}).$

Suppose that Ξ is directionally differentiable at every point in \mathcal{O} and that $\mathcal{J}\Psi(\bar{x}): \overline{X \to Y}$ is <u>onto</u>. Then it holds that

 $\partial_B \Phi(\bar{x}) = \partial_B \Xi(\bar{y}) \mathcal{J} \Psi(\bar{x}),$

where $\Phi: \widehat{N} \to Z$ is defined by

 $\Phi(x) := \Xi(\Psi(x)), \quad x \in \widehat{N}.$

Proof. By shrinking \widehat{N} if necessary, we may assume that $\Xi(\widehat{N}) \subseteq \mathcal{O}$. Then Ξ is Lipschitz continuous and directionally differentiable on \mathcal{O} . By further shrinking \widehat{N} if necessary, we may also assume that for each $x \in \widehat{N}$, $\mathcal{J}\Psi(x)$ is onto.

We shall first show that Φ is F-differentiable at $x \in \widehat{N}$ if and only if Ξ is F-differentiable at $\Psi(x)$, which ensures that

 $\partial_B \Phi(\bar{x}) \subseteq \partial_B \Xi(\bar{y}) \mathcal{J} \Psi(\bar{x}).$

Certainly, Φ is F-differentiable at $x \in \widehat{N}$ if Ξ is F-differentiable at $\Psi(x)$. Now, suppose that Φ is F-differentiable at $x \in \widehat{N}$. Then, since Ξ is directionally differentiable at $\Psi(x)$, for any $d \in X$ we have

 $\mathcal{J}\Phi(x)d = \Xi'(\Psi(x); \mathcal{J}\Psi(x)d),$

which implies that for any
$$s, t \in \Re$$
 and $u, v \in X$,

$$\Xi'(\Psi(x); s\mathcal{J}\Psi(x)u + t\mathcal{J}\Psi(x)v) = \Xi'(\Psi(x); \mathcal{J}\Psi(x)(su + tv))$$

$$= \mathcal{J}\Phi(x)(su+tv)$$

 $= s\mathcal{J}\Phi(x)u + t\mathcal{J}\Phi(x)v$

$$= s\Xi'(\Psi(x); \mathcal{J}\Psi(x)u) + t\Xi'(\Psi(x); \mathcal{J}\Psi(x)v).$$

By the surjectivity of $\mathcal{J}\Psi(x)$, we can conclude that $\Xi'(\Psi(x); \cdot)$ is a linear operator and so Ξ is Gâteau differentiable at $\Psi(x)$. Since Ξ is assumed to be locally Lipschitz continuous on \mathcal{O} , Ξ is F-differentiable at $\Psi(x)$.

Next, we show that the second half inclusion holds:

 $\partial_B \Phi(\bar{x}) \supseteq \partial_B \Xi(\bar{y}) \mathcal{J} \Psi(\bar{x}).$

Let $W \in \partial_B \Xi(\bar{y})$. Then there exists a sequence $\{y^k\}$ in \mathcal{O} converging to \bar{y} such that Ξ is F-differentiable at y^k and $W = \lim_{k \to \infty} \mathcal{J}\Xi(y^k)$.

By applying the classical Inverse Function Theorem to

$$\Psi\left(\bar{x} + \mathcal{J}\Psi(\bar{x})^*(y - \bar{y})\right) - \Psi(\bar{x}) = 0,$$

we obtain that there exists a sequence $\{\tilde{y}^k\}$ in \mathcal{O} converging to \bar{y} such that

$$\Psi\left(\bar{x} + \mathcal{J}\Psi(\bar{x})^*(\tilde{y}^k - \bar{y})\right) - \Psi(\bar{x}) = y^k - \Psi(\bar{x})$$

for all k sufficiently large.

Let $\tilde{x}^k := \bar{x} + \mathcal{J}\Psi(\bar{x})^*(\tilde{y}^k - \bar{y})$. Then $y^k = \Psi(\tilde{x}^k)$ and Φ is F-differentiable at \tilde{x}^k with

$$\mathcal{J}\Phi(\tilde{x}^k) = \mathcal{J}\Xi(y^k)\mathcal{J}\Psi(\tilde{x}^k).$$

By using the fact that $\tilde{y}^k \to \bar{y}$ implies $\tilde{x}^k \to \bar{x}$, we know that there exists a $V \in \partial_B \Phi(\bar{x})$ such that

 $W\mathcal{J}\Psi(\bar{x}) = \lim_{k \to \infty} \mathcal{J}\Xi(y^k) \lim_{k \to \infty} \mathcal{J}\Psi(\tilde{x}^k) = \lim_{k \to \infty} \mathcal{J}\Phi(\tilde{x}^k) = V \in \partial_B \Phi(\bar{x}).$

This completes the proof.

Proposition 2.9 For any $V \in \partial_B \Pi_{\mathcal{S}^p_+}(A)$ (respectively, $\partial \Pi_{\mathcal{S}^p_+}(A)$), there exists a $W \in \partial_B \Pi_{\mathcal{S}^{|\beta|}_+}(0)$ (respectively, $\partial \Pi_{\mathcal{S}^{|\beta|}_+}(0)$) such that

$$V(H) = P \begin{bmatrix} \widetilde{H}_{\alpha\alpha} & \widetilde{H}_{\alpha\beta} & U_{\alpha\gamma} \circ \widetilde{H}_{\alpha\gamma} \\ \widetilde{H}_{\alpha\beta}^T & W(\widetilde{H}_{\beta\beta}) & 0 \\ \widetilde{H}_{\alpha\gamma}^T \circ U_{\alpha\gamma}^T & 0 & 0 \end{bmatrix} P^T \quad \forall H \in \mathcal{S}^p,$$

$$(11)$$

where $\tilde{H} := P^T H P$.

Conversely, for any $W \in \partial_B \Pi_{\mathcal{S}^{|\beta|}_+}(0)$ (respectively, $\partial \Pi_{\mathcal{S}^{|\beta|}_+}(0)$), there exists a $V \in \partial_B \Pi_{\mathcal{S}^p_+}(A)$ (respectively, $\partial \Pi_{\mathcal{S}^p_+}(A)$) such that (11) holds. **Proof.** We only need to prove that (11) holds for $V \in \partial_B \Pi_{\mathcal{S}^p_+}(A)$ and $W \in \partial_B \Pi_{\mathcal{S}^{|\beta|}_+}(0)$.

Let $\Theta(\cdot) := \Pi'_{\mathcal{S}^p_+}(A; \cdot)$. Define $\Psi : \mathcal{S}^p \to \mathcal{S}^p$ by $\Psi(H) := P^T H P$, $H \in \mathcal{S}^p$ and $\Xi : \mathcal{S}^p \to \mathcal{S}^p$ by

$$\Xi(B) := P \begin{bmatrix} B_{\alpha\alpha} & B_{\alpha\beta} & U_{\alpha\gamma} \circ B_{\alpha\gamma} \\ B_{\alpha\beta}^T & \Pi_{\mathcal{S}^{|\beta|}_+}(B_{\beta\beta}) & 0 \\ B_{\alpha\gamma}^T \circ U_{\alpha\gamma}^T & 0 & 0 \end{bmatrix} P^T, \quad B \in \mathcal{S}^p.$$

Then we have

 $\Theta(H) = \Xi(\Psi(H)), \quad H \in \mathcal{S}^p.$

Since $\Pi_{\mathcal{S}^{|\beta|}_+}$ is directionally differentiable everywhere and $\mathcal{J}\Psi(H): \mathcal{S}^p \to \mathcal{S}^p$ is onto, we know from Proposition 2.8 that

 $\partial_B \Theta(0) = \partial_B \Xi(0) \mathcal{J} \Psi(0).$

This, together with Proposition 2.7, completes the proof.

Next, we consider an application of the variational analysis of the metric projector to a financial engineering problem: Given a symmetric matrix $G \in S^n$, its nearest correlation matrix is the optimal solution to

$$\min \quad \frac{1}{2} \| G - X \|^2$$

s.t. $X_{ii} = 1, \quad i = 1, \dots, n,$ (12)
 $X \in \mathcal{S}^n_+.$

Define: $\mathcal{A}: \mathcal{S}^n \to \Re^n$ by

$$\mathcal{A}(X) = (X_{11}, X_{22}, \dots, X_{nn})^T.$$

The adjoint of \mathcal{A} is given by

$$\mathcal{A}^*(y) = \operatorname{diag}(y_1, y_2, \dots, y_n).$$

Then, by using the Karush-Kuhn-Tucker (KKT) theory, we may solve the correlation matrix problem by solving the equation:

$$F(y) := \mathcal{A} \left(G + \mathcal{A}^* y \right)_+ - e = 0, \quad y \in \Re^n,$$

where $e \in \Re^n$ is the vector of all ones.

Let y^* be a root of F(y) = 0. Then we can recover the optimal solution to the correlation matrix problem by letting

$$X^* = (G + \mathcal{A}^* y^*)_+ \ .$$



In numerical computations, we use the following globalized Newton's method for solving the dual problem. Recall that for any $y \in \Re^n, \nabla \theta(y) = F(y) - e.$

Algorithm 2.1 (Newton's Method)

Step 0. Given $y^0 \in \Re^n$, $\eta \in (0, 1)$, $\rho, \sigma \in (0, 1/2)$. k := 0.

Step 1. Select an element $V_k \in \partial F(y^k)$ and apply the conjugate gradient (CG) method of Hestenes and Stiefel to find an approximate solution d^k to

$$\nabla\theta(y^k) + V_k d = 0 \tag{13}$$

such that

$$\left\|\nabla\theta(y^{k}) + V_{k}d^{k}\right\| \le \eta_{k}\left\|\nabla\theta(y^{k})\right\|$$
(14)

where $\eta_k := \min\{\eta, \|\nabla \theta(y^k)\|\}.$

Step 2. (continued)

If (14) is not achievable or if the condition

$$\nabla \theta(y^k)^T d^k \le -\eta_k \|d^k\|^2 \tag{15}$$

is not satisfied, let $d^k := -B_k^{-1} \nabla \theta(y^k)$, where B_k is any symmetric positive definite matrix in \mathcal{S}^n .

Let m_k be the smallest nonnegative integer m such that

$$\theta(y^k + \rho^m d^k) - \theta(y^k) \le \sigma \rho^m \nabla \theta(y^k)^T d^k.$$

Set $t_k = \rho^{m_k}$ and $y^{k+1} = y^k + t_k d^k$.

Step 3. Replace k by k + 1 and go to Step 1.

Theorem 2.1 Suppose that in Algorithm 2.1 both $\{||B_k||\}$ and $\{||B_k^{-1}||\}$ are uniformly bounded. Then the iteration sequence $\{y^k\}$ generated by Algorithm 2.1 converges to the unique solution y^* of F(y) = 0 quadratically.

For details on the above Newton's method for computing the nearest correlation matrix problem, see

• H.-D. QI AND D. SUN. A quadratically convergent Newton method for computing the nearest correlation matrix. *SIAM Journal on Matrix Analysis and Applications* (2006).

Source code in MatLab is available at http://www.math.nus.edu.sg/ matsundf

The material on the basic properties of metric projectors is quite standard. For the properties on the Jacobian of metric projectors, see the following papers:

- D. SUN AND J. SUN. Semismooth matrix valued functions. Mathematics of Operations Research 27 (2002) 150–169.
- J.S. PANG, D. SUN, AND J. SUN. Semismooth homeomorphisms and strong stability of semidefinite and Lorentz complementarity problems. *Mathematics of Operations Research* 28 (2003) 39–63.

- F. MENG, D. SUN, AND G. ZHAO. Semismoothness of solutions to generalized equations and the Moreau-Yosida regularization. *Mathematical Programming* 104 (2005) 561–581.
- D. SUN. The strong second order sufficient condition and constraint nondegeneracy in nonlinear semidefinite programming and their implications. *Mathematics of Operations Research* 31 (2006).