AN TYPE OF ABS ALGORITHM FOR SOLVING SINGULAR NONLINEAR SYSTEMS WITH RANK DEFECTS(2)

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Consider the following nonlinear system

$$F(x) = 0 (1)$$

where $x \ 2 \ R^n$, $F(x) = (f_1(x); f_2(x); \dots; f_n(x))^T$. We assume that there exists a solution x^{α} of (1), $F(x^{\alpha}) = 0$, $F^{(0)}$ is Lipschitzian around x^{α} and furthermore that

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$$< \operatorname{rank}(F^{\emptyset}(x^{n})) = n_{i} r; r > 1$$

Let: $\lambda_{i;j} = v_{i}^{\mathsf{T}} F^{\emptyset}(x^{n}) u_{i} u_{j}; \operatorname{andg}_{in}^{\mathsf{T}} = v_{i}^{\mathsf{T}} F^{\emptyset}(x^{n}) u_{i} u_{i}$ (2)
 $\det(\lambda_{i;j}) \in 0; g_{in}^{\mathsf{T}} \in 0$

where $u_1; u_2; \dots; u_r$ and $v_1; v_2; \dots; v_r$ are arbitrary orthogonal vector sets such that

$$Null(F^{\emptyset}(x^{x})) = spanfu_{1}; u_{2}; \dots; u_{r}g$$

$$Null(F^{\emptyset}(x^{x})^{T}) = spanfv_{1}; v_{2}; \dots; v_{r}g$$
(3)

And Let

$$N = (u_1; u_2; \dots; u_r); V = (v_1; v_2; \dots; v_r)$$

Taking r £ r matrix P; Q; Q ¼ V , P ¼ U; Let

$$(P^T U)^{i-1} = (s_1; s_2; \dots; s_r); (Q^T V)^{i-1} = (h_1; h_2; \dots; h_r)$$

We constitute a new function

$$T(x) = (F(x); w_1(x); w_2(x); :::; w_r(x))^T$$

,where $w_i(x) = h_i^T V^T F^0(x) U s_i$, then $T(x^x) = 0$ and $T^0(x^x)$ is of full rank. By combining the discreted ABS algorithm and extending ideas of Hoy and Schwetlick presented in 1990,we have established a modi⁻ed ABS method and discussed its Q-superlinear convergence.

[Notice]: for a particular situation of rank($F^{0}(x^{n})$) = n; 1, we have published the corresponding result in Korean J.Comput.Appl.Math.(2002), Vol.9, No.1.