

## Subject Description Form

<b>Subject Code</b>	AAE6103
<b>Subject Title</b>	Advanced Control Theory for Aircraft
<b>Credit Value</b>	3
<b>Level</b>	6
<b>Pre-requisite/ Co-requisite/ Exclusion</b>	N/A
<b>Objectives</b>	To provide students with theories of advanced flight control including linear and nonlinear analysis and control methodologies, backstepping, feedback linearization, sliding mode control, adaptive control.
<b>Intended Learning Outcomes</b>	<p>Upon completion of the subject, students will be able to:</p> <ul style="list-style-type: none"> <li>a) possess the essential knowledge and skills in advanced flight control theories.</li> <li>b) design flight controllers which can deal with real-life model uncertainties or disturbances.</li> <li>c) analyze the closed-loop stability of the designed flight controller.</li> <li>d) apply the advanced control theories to control the aircraft.</li> </ul>
<b>Subject Synopsis/ Indicative Syllabus</b>	<p><b>Introduction of Flight control</b> – nonlinearities, model uncertainties, wind disturbances.</p> <p><b>Linear control and analysis</b> – state-space representation, state-space solutions, stability, controllability, observability, state feedback design, output feedback design.</p> <p><b>Nonlinear control and analysis</b> – Lyapunov’s indirect and direct methods, invariant set theorem, Barbalat’s lemma.</p> <p><b>Backstepping</b> – stabilization by backstepping.</p> <p><b>Input-output linearization</b> – asymptotic tracking by input-output linearization, normal form and zero dynamics.</p> <p><b>Sliding control</b> – sliding surface, disturbance rejection, robustness.</p> <p><b>Adaptive control</b> – adaptive control for aircrafts, adaptive control for Euler-Lagrange systems.</p>

<b>Teaching/Learning Methodology</b>	1. The teaching and learning methods include lecture/tutorial sessions, homework assignments and mini project.				
	2. Scientific examples and problems are raised and discussed in class/tutorial sessions.				
	<b>Teaching/Learning Methodology</b>	<b>Intended subject learning outcomes</b>			
		a	b	c	d
	1. Lecture/Tutorial	√	√	√	√
2. Homework assignment	√	√	√	√	
3. Mini project	√	√	√	√	

<b>Assessment Methods in Alignment with Intended Learning Outcomes</b>	Specific assessment methods/tasks	% weighting	Intended subject learning outcomes to be assessed (Please tick as appropriate)			
			a	b	c	d
	1. Homework assignment	20%	√	√	√	√
	2. In-class test	30%	√	√	√	√
	3. Final examination	50%	√	√	√	√
Total	100 %					
<p>Explanation of the appropriateness of the assessment methods in assessing the intended learning outcomes:</p> <p>Overall Assessment:  0.5 x End of Subject Examination + 0.5 x Continuous Assessment</p> <p>The continuous assessment consists of two components: homework assignments and an in-class test. Homework assignments are aimed at evaluating the progress of students' study, assisting them in self-monitoring of fulfilling the respective subject learning outcomes, and enhancing the integration of the knowledge learned. The in-class test serves to evaluate the students' capability of analyze the performance of complex aircraft systems using linear control technique, Lyapunov and Lyapunov-like methodologies.</p> <p>The final examination is used to assess the knowledge acquired by the students for understanding, analyzing, and solving the control problems of aircraft systems critically and independently; as well as to determine the degree of achieving the subject learning outcomes.</p>						

<b>Student Study Effort Expected</b>	Class contact:	
	▪ Lecture	39 Hrs.
	Other student study effort:	
	▪ Literature Review and Self-learning	30 Hrs.
	▪ Assignments	30 Hrs.
	▪ Software design (take home exercises)	12 Hrs.
	Total student study effort	111 Hrs.
<b>Reading List and References</b>	<ol style="list-style-type: none"> <li>1. H. K. Khalil, <i>Nonlinear Systems</i>. 2002, Third Edition</li> <li>2. J.J. Slotine and W. Li, <i>Applied Nonlinear Control</i>, Prentice Hall Englewood Cliffs, 1991.</li> <li>3. C.-T. Chen, <i>Linear Systems Theory and Analysis (3<sup>rd</sup> Edition)</i>, Oxford University Press, 1999.</li> <li>4. E. Shtessel, Y., Edwards, C., Fridman, L., Levant, A., <i>Sliding Mode Control and Observation</i>. 2014: Springer, Latest Edition</li> <li>5. Mclean, D. <i>Automatic Flight Control Systems</i>, Prentice Hall International, Latest Edition.</li> </ol>	

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